

Xsens Sirius AHRS

- Achieve new levels of accuracy with high-quality calibrated roll, pitch and yaw data
- > Rugged and military standard certified
- > Flexible interfaces and protocols for seamless integration





Description

The Xsens Sirius AHRS features vibration- and shock-rejecting gyroscopes and offers high-quality inertial and orientational data, even in the harshest environments.

With Xsens technology inside, the all-in-one sensor system supports optimized temperature calibration, high-frequency outputs, and has configurable output settings for synchronization with any third-party device.

The Xsens Sirius AHRS is supported by the MT Software Suite which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms.

- > White label options available
- > 3D models available on request

Sensor fusion performance

Roll, Pitch	0.2 ° RM
Yaw/Heading	<1 ° RMS
Strandown Integration (SDI)	Yes

Gyroscope

Standard full range	± 300 °/s
In-run bias stability	 7°/h
Bandwidth (-3dB)	 400 Hz
Noise Density	0.003°/s/√Hz
g-sensitivity (calibr.)	0.08°/s/g

Accelerometer

Standard full range	±8g
In-run bias stability	15 µg
Bandwidth (-3dB)	470 Hz
Noise Density	15 µg/√Hz

Magnetometer

Standard full range	±8G
Total RMS noise	1 mG
Non-linearity	0.2%
Resolution	0.25 mg

Mechanical	
IP-rating	IP68
Operating Temperature	-40 to +85
Casing material	Aluminum

Mounting orientation	No restriction, full 360° in all axes
Dimensions	56.50 x 40.90 x 24.75 mm
Connector	Main: ODU (AMC HD 12 pins)
Weight	78.5g grams
Certifications	CE, FCC, RoHS, MIL-STD-202,
	ITAR free

Electrical

Input voltage	4.5V-24V
Power consumption (typ)	520 mW

Interfaces / IO

Interfaces	RS232, RS422, CAN
Sync Options	SyncIn, SyncOut, ClockSync
Protocols	Xbus, ASCII (NMEA), CAN
Clock drift	10 ppm (or external)
Output Frequency	Up to 400Hz
Built-in-self test	Gyr, Acc, Mag

Software Suite	
GUI (Windows/Linux)	MT Manager, Firmware updater,
	Magnetic Field Mapper
SDK (Example code)	C++, C#, Python, Matlab,
	Public source code
Drivers	LabVIEW, ROS, GO
Support	Online manuals, community
	and knowledge base